

**Nate.**

# NR2M

## Robotic Arm for Industrial Automation

NR2 is a range of compact and robust robotic arms, designed and manufactured in France. It is intended for industrial companies, laboratories and integrators looking to rapidly deploy reliable and scalable robotic solutions.



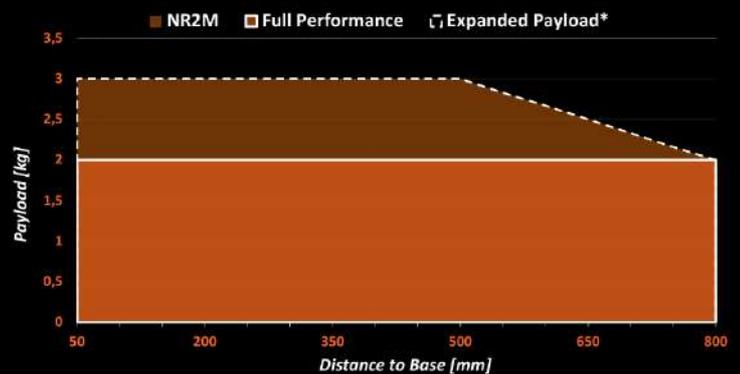
## General Specifications

Degrees of Freedom :	6
Payload, kg :	2
Reach, mm :	800
Pose Repeatability, mm : (ISO 9283)	±0,1
Interfaces :	Ethernet / USB / I/O
Programming :	App. NiryoStudio for Nate

## Kinematics & Motion Range

Max TCP speed, m/s :	3	
Axis Limits	Working Range	Maximum Speed
Joint 1 :	340 °	180 °/s
Joint 2 :	180 °	180 °/s
Joint 3 :	185 °	180 °/s
Joint 4 :	340 °	240 °/s
Joint 5 :	190 °	240 °/s
Joint 6 :	340 °	240 °/s

## Payload Diagram



\*Note : With specific motion parameters settings.

## Environmental & Safety

IP Classification :	IP54
Operating Temperature, °C :	5-45
Noise, dB :	< 70
Humidity, % :	≤ 75
Power Supply :	100-240 VAC, 50-60 Hz
Power Consumption, W :	300
Safety Standard :	ISO 10218-1
Certification :	CE



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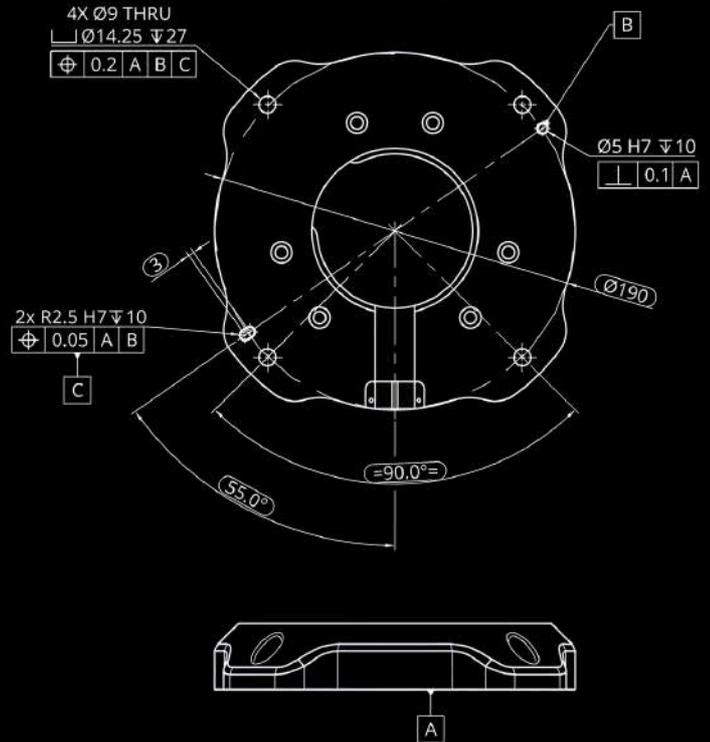
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Robotic Arm for Industrial Automation

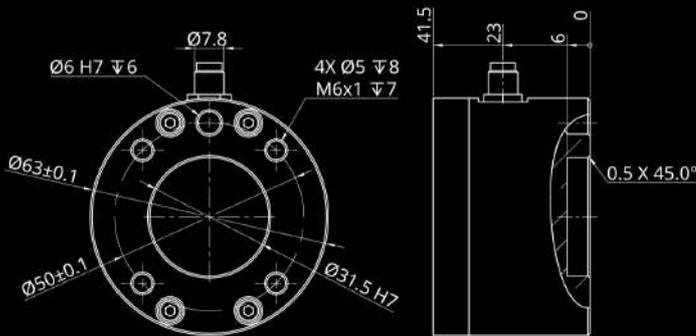
## Physical Attributes

Footprint, mm :	Ø 190		
Materials :	Aluminium, Plastic, Steel		
Weight, kg :	17		
Tool Interface :	ISO 9409-1-50-4-M6		
I/O for Tool	Digital In	Digital Out	Analog in
	2	2	2
Connector Type :	M8 8-pin		
Tool Power Supply :	12V / 24V 600 mA		

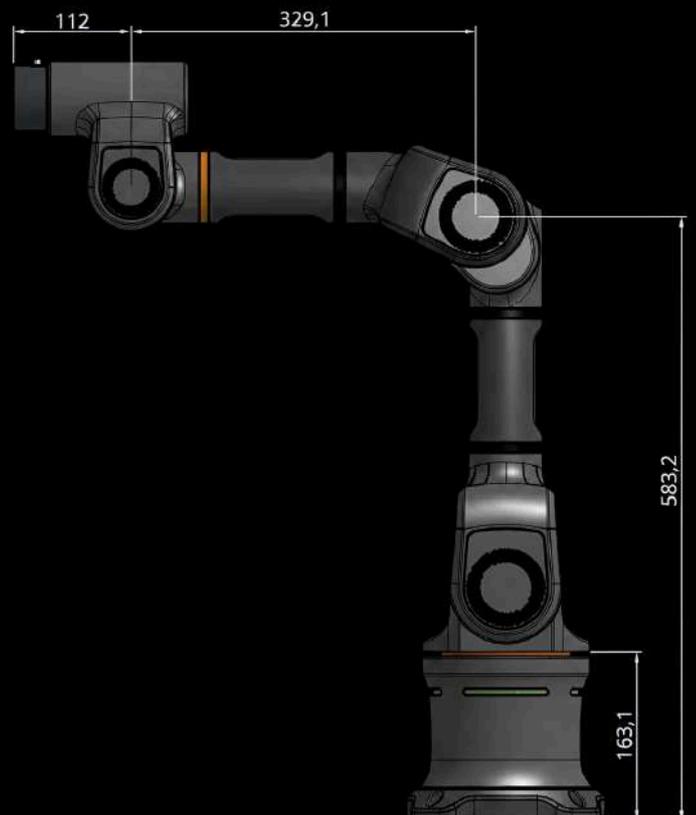
## Base Mounting View



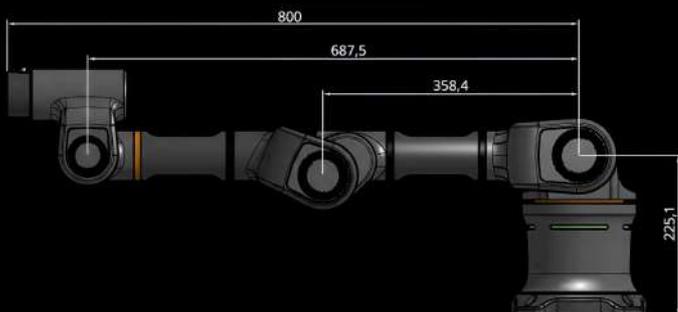
## Tool Flange (ISO 9409-1)



## Dimensions



## Maximum Reach



# Nate. NR2L

## Robotic Arm for Industrial Automation

NR2 is a range of compact and robust robotic arms, designed and manufactured in France. It is intended for industrial companies, laboratories and integrators looking to rapidly deploy reliable and scalable robotic solutions.



## General Specifications

Degrees of Freedom :	6
Payload, kg :	2*
Reach, mm :	1100
Pose Repeatability, mm : (ISO 9283)	±0,1
Interfaces :	Ethernet / USB / I/O
Programming :	App. NiryoStudio for Nate

\*Note : Reach dependent. See Payload diagram for specific limits.

## Kinematics & Motion Range

Max TCP speed, m/s :	3	
Axis Limits	Working Range	Maximum Speed
Joint 1 :	340 °	180 °/s
Joint 2 :	180 °	180 °/s
Joint 3 :	185 °	180 °/s
Joint 4 :	340 °	240 °/s
Joint 5 :	190 °	240 °/s
Joint 6 :	340 °	240 °/s

## Payload Diagram



\*Note : With specific motion parameters settings.

## Environmental & Safety

IP Classification :	IP54
Operating Temperature, °C :	5-45
Noise, dB :	< 70
Humidity, % :	≤ 75
Power Supply :	100-240 VAC, 50-60 Hz
Power Consumption, W :	300
Safety Standard :	ISO 10218-1
Certification :	CE

Nate.

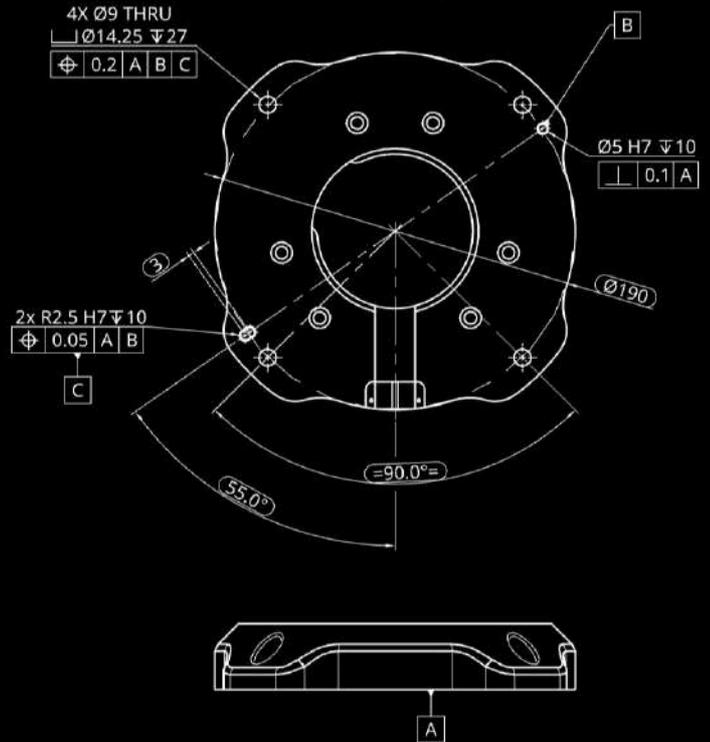
# NR2L

Robotic Arm for Industrial Automation

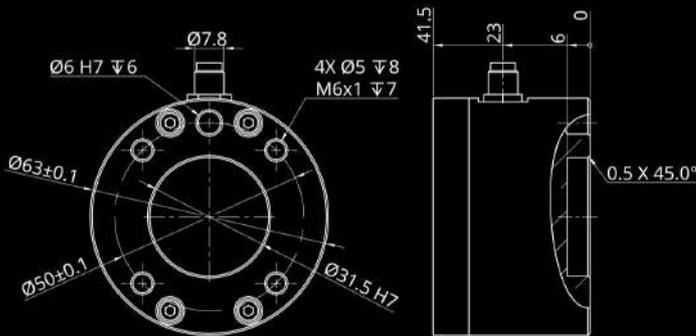
## Physical Attributes

Footprint, mm :	Ø 190		
Materials :	Aluminium, Plastic, Steel		
Weight, kg :	19		
Tool Interface :	ISO 9409-1-50-4-M6		
I/O for Tool	Digital In	Digital Out	Analog in
	2	2	2
Connector Type :	M8 8-pin		
Tool Power Supply :	12V / 24V 600 mA		

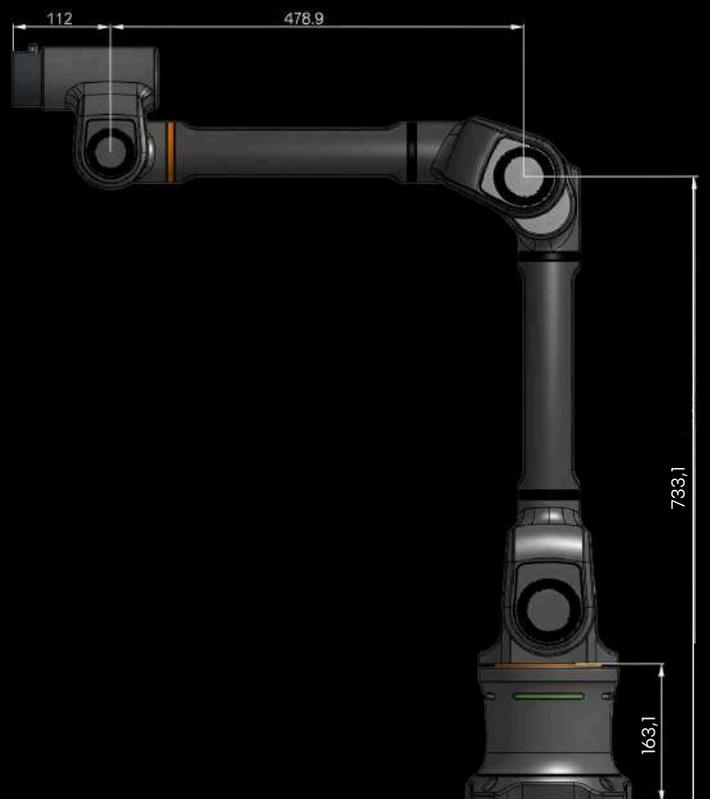
## Base Mounting View



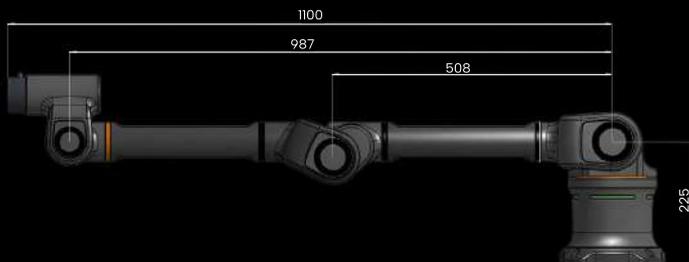
## Tool Flange (ISO 9409-1)



## Dimensions



## Maximum Reach



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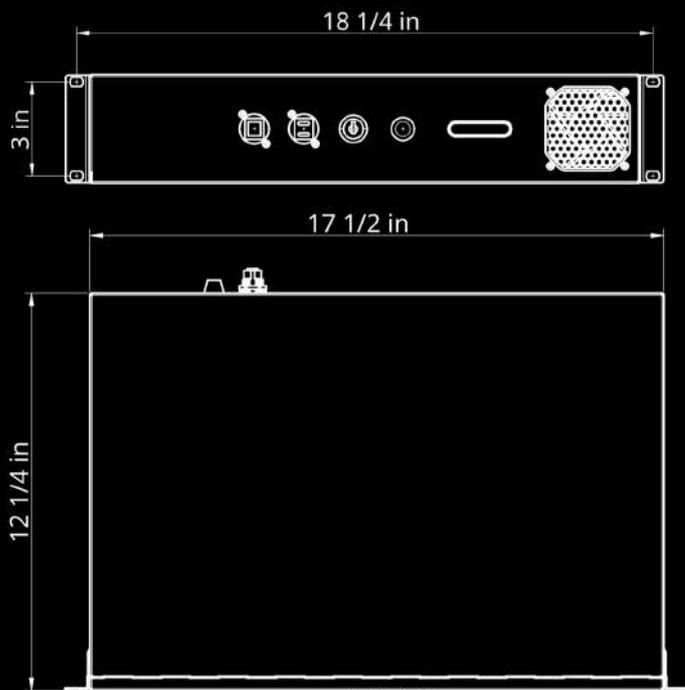
# NC1000

**Powerful and Robust Robot Controller**

## General Specifications

Power Source :	100-240 VAC, 50-60 Hz
Hardware interfaces :	RJ45 Ethernet Gb/s USB Type-C (Data) USB Type-C (Power & Data) Wi-Fi 6 (802.11ax) BLE (Bluetooth Low Energy)
Industrial Protocols :	ModBus TCP Ethernet/IP
Maximum Power, W :	400
Dimensions, mm (W x D x H) :	445 x 311 X 76
Weight, kg :	8
Robot Cable Length, m :	3
IP Classification :	IP20
Certification :	CE

## Technical Drawings



## I/O Panel

### Safety I/O

Safety Input :	5
Safety Output :	2

### Standard I/O

Digital In :	8
Digital Out :	8
Analog In :	2
Analog Out :	2

### Others I/O

Auxiliary 24 V DC Power Outputs :	8
Remote Power Input :	1

## Pinouts Detail

